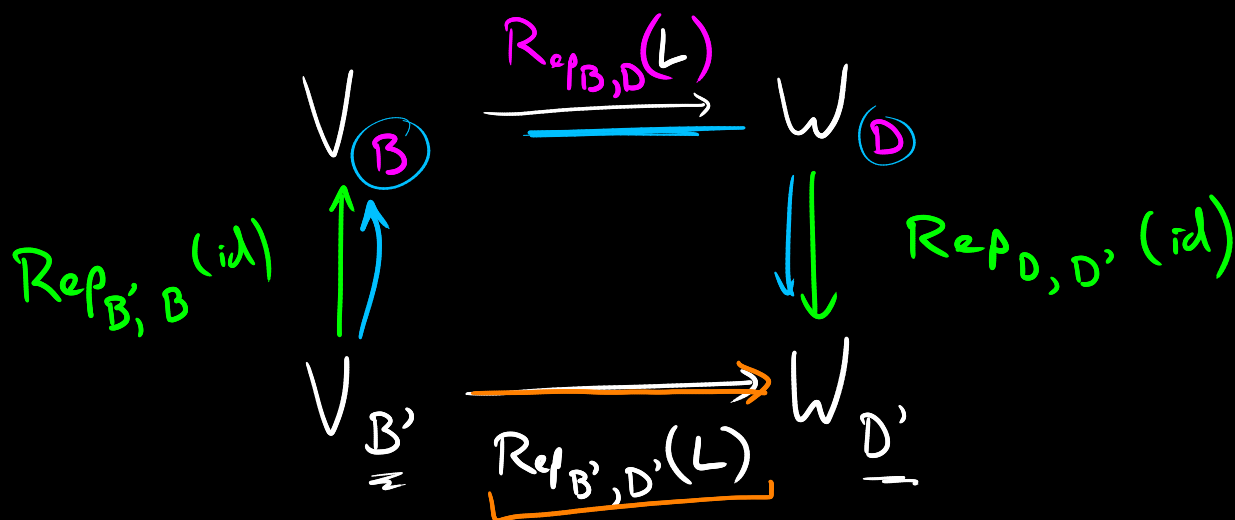


Overview: Studying linear maps.



$$\text{Rep}_{B',D'}(L) = \text{Rep}_{D,D'}(\text{id}) \cdot \text{Rep}_{B,D}(L) \cdot \text{Rep}_{B',B}(\text{id})$$

NB: The order of multiplication of matrices DOES matter...

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$$
$$\begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\left. \begin{array}{l} (f \circ g)(x) = f(g(x)) \\ A \xrightarrow{g} B \xrightarrow{f} C \end{array} \right\}$$

Defn: A matrix A is similar to matrix B when there is an invertible matrix P with $B = P^{-1}AP$.

Ex: $A = \begin{bmatrix} 1 & 1 \\ 2 & 0 \end{bmatrix}$ $P = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$.

So $P^{-1} = \frac{1}{1 \cdot 1 - 0 \cdot 0} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ inverse formula for 2×2 matrices.

Then $B = P^{-1}AP = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 2 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$
 $= \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ is similar to A .

(by definition)

□

NB: Similarity of $n \times n$ matrices is an equivalence relation:

- ① Every matrix is similar to itself. ($A = I^{-1} A I$)
- ② If A is similar to B , then B is similar to A .
(If $B = P^{-1} A P$, then $P B = A P$, so $P B P^{-1} = A$)
- ③ If A is similar to B and B is similar to C , then A is similar to C .
(if $B = P^{-1} A P$ and $C = Q^{-1} B Q$, then
 $C = Q^{-1} B Q = Q^{-1} (P^{-1} A P) Q = \underline{(PQ)^{-1}} \underline{A} \underline{(PQ)}$)

Q: When are two matrices similar?

A: A and B are similar when they represent the same linear operator w.r.t. different bases.

$$\begin{array}{ccc} \mathbb{R}_B^n & \xrightarrow{A} & \mathbb{R}_B^n \\ \uparrow P & & \downarrow P^{-1} \\ \mathbb{R}_D^n & \xrightarrow{C} & \mathbb{R}_D^n \end{array} \quad \begin{array}{l} P = \text{Rep}_{D,B}(\text{id}) \\ C = \underline{P^{-1}} \underline{A} \underline{P} \end{array}$$

Point: Similarity is all about basis change!

Ex: Let $L_0: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ take $L_0\left(\begin{pmatrix} x \\ y \\ z \end{pmatrix}\right) = \begin{pmatrix} x+y+z \\ y+z \\ z \end{pmatrix}$

and $L_1: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ take $L_1\left(\begin{pmatrix} x \\ y \\ z \end{pmatrix}\right) = \begin{pmatrix} 2x+y-z \\ x-y+z \\ z \end{pmatrix}$.

w.r.t. \mathcal{E}_3 we have $\text{Rep}_{\mathcal{E}_3, \mathcal{E}_3}(L_0) = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} = M$.

OTOH $\text{Rep}_{\mathcal{E}_3, \mathcal{E}_3}(L_1) = \begin{bmatrix} 2 & 1 & -1 \\ 1 & 0 & 1 \\ 0 & 0 & 1 \end{bmatrix} = N$. Now

we compute the determinants of M and N :

$$\det(M) = \det \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} = 1.$$

$$\det(N) = \det \begin{bmatrix} 2 & 1 & -1 \\ 1 & -1 & 1 \\ 0 & 0 & 1 \end{bmatrix} = 0 - 0 + 1 \det \begin{bmatrix} 2 & 1 \\ 1 & -1 \end{bmatrix} \\ = 2 \cdot (-1) - 1 \cdot 1 = -3$$

so M and N are not similar.

□

NB: If M is similar to N , then $M = P^{-1}NP$

$$\text{implies } \det(M) = \det(P^{-1}NP) = \det(P^{-1}) \det(N) \det(P) \\ = \frac{1}{\det(P)} \det(N) \det(P) = \det(N).$$

Ex: $I_2 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ and $J = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$ both have

$\det(I_2) = 1$ and $\det(J) = 1$, but I_2 and J are not similar... For every P , invertible:

$$P^{-1}I_2P = P^{-1}P = I_2, \text{ so } I_2 \text{ is } \underline{\underline{NOT}} \text{ similar to } J.$$

Q: When is a matrix M similar to a diagonal matrix?

EIGENVECTORS AND EIGENVALUES

Defn: A linear operator L has eigenvector $0 \neq v \in \text{dom}(L)$ with eigenvalue λ when $L(v) = \lambda v$.

Prop: Given eigenvalue λ for L , the eigenspace $V_\lambda = \{v \in \text{dom}(L) : L(v) = \lambda v\}$ is a subspace of $\text{dom}(L)$.

Method to compute eigenvalues of M (\leftarrow rep. a lin map).

① Compute characteristic polynomial $P_M(\lambda) = \det(M - \lambda I)$.

② Compute roots of $P_M(\lambda)$. (i.e. solve $P_M(\lambda) = 0$).

③ Those roots are all the eigenvalues!

$$\left(\begin{array}{l} (M - \lambda I)v = \vec{0} \Leftrightarrow \boxed{Mv = \lambda v} \\ \updownarrow \\ \boxed{\det(M - \lambda I) = 0} \end{array} \right) \begin{array}{l} \uparrow \\ \text{since } v \neq \vec{0} \end{array} \quad \star$$

Ex: Let $M = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$. $P_M(\lambda) = \det \begin{bmatrix} 1-\lambda & 1 \\ 0 & 1-\lambda \end{bmatrix} = \boxed{(1-\lambda)^2}$

has roots $\lambda = 1$. Thus M has eigenvalue $\lambda = 1$. \square

Defn: The algebraic multiplicity of eigenvalue $\lambda = \alpha$ is the corresponding power of $\lambda - \alpha$ in a complete factorization of $P_M(\lambda)$.

Recall: Polynomial $f(x)$ has $f(\alpha) = 0$ iff $x - \alpha$ is a factor of $f(x)$...

NB: In this example above ($M = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$), $\lambda = 1$ had algebraic multiplicity 2.

Q: How do we compute eigenspaces (i.e. the eigenvectors)?

Method to Compute Eigenspaces:

① Compute eigenvalues via $P_M(\lambda) = 0$.

② The eigenspace associated to $\lambda = \alpha$ is precisely $\text{null}(M - \alpha I)$ (i.e. $V_\alpha = \text{null}(M - \alpha I)$).

Ex: For $M = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$, $P_M(\lambda) = (1-\lambda)^2$.

$$\underline{\lambda=1}: \text{null} \begin{bmatrix} 1-\lambda & 1 \\ 0 & 1-\lambda \end{bmatrix} = \text{null} \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} = V_1$$

$$\text{RREF}(M - \lambda I) = \text{RREF} \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$$

yells null space: $\begin{bmatrix} x \\ y \end{bmatrix} \in \text{null}(M - \lambda I)$ iff $y = 0$

i.e. $\left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right\}$ is a basis of V_1 . \square

Ex: Let $M = \begin{bmatrix} 1 & 0 & 2 \\ 0 & 3 & 0 \\ 2 & 0 & 1 \end{bmatrix}$.

$$P_M(\lambda) = \det(M - \lambda I) = \det \begin{bmatrix} 1-\lambda & 0 & 2 \\ 0 & 3-\lambda & 0 \\ 2 & 0 & 1-\lambda \end{bmatrix} \leftarrow$$

$$= -0 + (3-\lambda) \det \begin{bmatrix} 1-\lambda & 2 \\ 2 & 1-\lambda \end{bmatrix} - 0$$

$$= (3-\lambda)((1-\lambda)^2 - 4)$$

$$= (3-\lambda)((1-\lambda)^2 - 2^2)$$

$$= (3-\lambda)(1-\lambda-2)(1-\lambda+2)$$

$$= (3-\lambda)(-1-\lambda)(3-\lambda) = (3-\lambda)^2(-1-\lambda)$$

\therefore eigenvalues $\lambda=3$ and $\lambda=-1$ w/ algebraic mult. 2 and 1 respectively. Now the eigenspaces:

$$\underline{\lambda=3}: M - 3I = \begin{bmatrix} 1-3 & 0 & 2 \\ 0 & 3-3 & 0 \\ 2 & 0 & 1-3 \end{bmatrix} = \begin{bmatrix} -2 & 0 & 2 \\ 0 & 0 & 0 \\ 2 & 0 & -2 \end{bmatrix} \leftarrow$$

which has $\text{RREF}(M - 3I) = \begin{bmatrix} 1 & 0 & -1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$.

$$\therefore \text{null}(M - 3I) \Rightarrow \begin{bmatrix} x \\ y \\ z \end{bmatrix} \text{ iff } x - z = 0 \text{ iff } \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} x \\ 0 \\ x \end{bmatrix} = \begin{bmatrix} x \\ 0 \\ x \end{bmatrix} + \begin{bmatrix} 0 \\ y \\ 0 \end{bmatrix}$$

thus $\left\{ \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \right\}$ is a basis of $\text{null}(M-3I) = V_3$.

$\lambda = -1$: $M+I = \begin{bmatrix} 1-(-1) & 0 & 2 \\ 0 & 3-(-1) & 0 \\ 2 & 0 & 1-(-1) \end{bmatrix} = \begin{bmatrix} 2 & 0 & 2 \\ 0 & 4 & 0 \\ 2 & 0 & 2 \end{bmatrix}$ which has

$\text{RREF}(M+I) = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, so we have computed

$\begin{bmatrix} x \\ y \\ z \end{bmatrix} \in V_{-1}$ iff $\begin{cases} x+z=0 \\ y=0 \end{cases}$ iff $\begin{cases} x=-z \\ y=0 \end{cases}$ iff $\begin{bmatrix} x \\ y \\ z \end{bmatrix} = t \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$.

so V_{-1} has basis $\left\{ \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} \right\}$. \square

Defn: The geometric multiplicity of eigenvalue $\lambda = \alpha$ is the dimension of the eigenspace V_α .

(i.e. $\text{geom mult} = \dim(V_\alpha)$).

NB: In the example above, 3 has $2 = \text{geom mult} = \text{alg mult}$ and -1 has $1 = \text{geom mult} = \text{alg mult}$.

Ex: $M = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$ but $p_M(\lambda) = (1-\lambda)^2$ but $\dim(V_1) = 1 \neq 2$.

so geometric mult does NOT always agree w/ alg mult. \square